

# SICONG JIANG

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## SUMMARY

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**Final-year McGill Ph.D. and Google DeepMind Research Intern** focusing on **AI Agents, Multimodal Model Evaluation, and Reward Modeling**. Recognized for developing **human-aligned reward models** and architecting **large-scale data/evaluation pipelines** from scratch. First-author contributor to top AI venues (**ICLR, EMNLP, ICRA, AISTATS**) with deep engineering proficiency in modern **LLM training paradigms**. **Actively seeking full-time industry roles starting in Fall 2026**.

## EDUCATION

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<b>McGill University</b> <i>Ph.D in Center for Intelligent Machines</i>	Jan 2022 – Present Quebec, Canada
<b>Georgia Institute of Technology</b> <i>Master of Electrical and Computer Engineering</i>	Sep 2019 – Dec 2021 Georgia, USA
<b>Northeastern University</b> <i>Bachelor of Electrical Engineering</i>	Sep 2015 – June 2019 Shenyang, China

## EXPERIENCE

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<b>Google Deepmind</b> <i>Research Intern</i>	Mar 2026 – Sep 2026 London, UK
<ul style="list-style-type: none"><li>• <b>Self-evolving agents</b>: Built iterative self-refinement loops for long-horizon tasks, with measurable improvements via evaluator-driven feedback.</li><li>• <b>LLM-as-a-judge reliability</b>: Developed rubric-based diagnostics and stress tests to characterize judge failure modes (inconsistency, prompt sensitivity) and improve feedback trustworthiness.</li></ul>	
<b>Abaka AI</b> <i>Director of Research, Founding Member of Technical Team</i>	Aug 2025 – Feb 2026 Palo Alto, California
<ul style="list-style-type: none"><li>• <b>Research (benchmarking &amp; evaluation)</b>: As a founding member of the Research team, led benchmarking and evaluation for <b>agentic</b> and <b>multimodal</b> LLMs; led <b>EditReward</b> and co-developed large-scale benchmarks including <b>SuperGPQA</b> and <b>VeriGUL</b>.</li><li>• <b>Advanced dataset &amp; pipeline design</b>: Led multiple <b>zero-to-one</b> pipeline builds—architecting and deploying high-difficulty datasets and production pipelines from scratch across <b>coding, IMO-level math, multimodal data, agentic trajectories</b>, and <b>RL</b> environments.</li><li>• Delivered <b>datasets and pipelines</b> used directly for <b>model training/evaluation</b> for multiple <b>frontier AI labs</b>.</li></ul>	
<b>Mercor</b> <i>Applied Scientist Intern</i>	May 2025 – Aug 2025 Remote
<ul style="list-style-type: none"><li>• <b>Data quality &amp; evaluation</b>: Designed multi-stage QA for large-scale LLM training annotations, improving consistency via calibration, automated checks, and targeted reviewer feedback loops.</li><li>• <b>Metrics &amp; analytics</b>: Built labeler-performance metrics and monitoring to detect systematic errors and guide guideline iterations for higher-quality training data.</li></ul>	

## SELECTED PUBLICATIONS

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\* indicates equal contribution. For full list, visit [Google Scholar](#).

- **[ICLR 2026]** Wu K\*, **Jiang S\***, Ku M, et al. *EditReward: A Human-Aligned Reward Model for Instruction-Guided Image Editing*.
- **[EMNLP 2025]** Qian K\*, **Jiang S\***, Zhong Y, et al. *AgentThink: A Unified Framework for Tool-Augmented Chain-of-Thought Reasoning in Vision-Language Models for Autonomous Driving*.
- **[ICRA 2026]** Luo Z\*, **Jiang S\***, Qian K\*, Huang Z, Miao J, et al. *FASIONAD+: Enhanced Safety in Autonomous Driving with Adaptive Feedback*.
- **[AISTATS 2025]** Liu F\*, **Jiang S\***, et al. *Adversarial Vulnerabilities in Large Language Models for Time Series Forecasting*.
- **[ICCV-W 2025]** **Jiang S\***, Huang Z\*, Qian K\*, et al. *A Survey on Vision–Language–Action Models for Autonomous Driving*.

## SKILLS

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- **Languages:** Python, SQL, Java, MATLAB
- **ML/LLM stack:** PyTorch, TensorFlow, HuggingFace; Scikit-learn, XGBoost; Pandas/NumPy
- **LLM alignment & evaluation:** reward modeling, preference data; SFT, LoRA, RLHF (PPO/DPO/GRPO); LLM-as-a-judge reliability, agent evaluation, red-teaming
- **Applied domains:** multimodal image editing; vision-language for autonomous driving; time-series forecasting robustness; simulation (CARLA, SUMO)

## SELECTED PROJECTS

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### **EditReward: A Human-Aligned Reward Model for Image Editing**

*Project Lead, Collaborated with University of Waterloo*

- Spearheaded a **human-aligned reward model** for instruction-guided image editing; engineered scalable pipelines to construct **EditReward-DATA (200K+ preference pairs)** and **EditReward-Bench**.
- Achieved broad industry adoption, with the benchmark and dataset utilized by leading research teams at **Meta, Google DeepMind, Apple, Adobe, Salesforce**; boosted GenAI-Bench by **+23%** over the Qwen2.5-VL baseline via reward-driven data curation.

### **Agent-Think: Tool-Augmented Reasoning in VLMs for Autonomous Driving**

*Project Lead, Collaborated with Xiaomi Inc. & Tsinghua University*

- Proposed **Agent-Think**, a VLM framework for autonomous driving that combines structured CoT with **tool-augmented** reasoning; built a pipeline to auto-generate self-verified VQA with CoT & tool-use.
- Fine-tuned Qwen2.5-VL-7B with **SFT + GRPO (LoRA)**, improving answer accuracy up to **+54%** and reasoning score up to **+33%** on public benchmarks.

### **Adversarial Attacks in LLM-based Time-Series Forecasting**

*Project Lead, McGill University*

- Designed a **gradient-free, black-box attack** suite for LLM-based forecasters, raising MAE/MSE up to **45%** with perturbations limited to **2%** of the input-signal mean.
- Curated an automated evaluation pipeline and collaborated with several time-series foundation model teams (**Amazon Chronos, Nixtla TimeGPT**).

## AWARDS

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**2021 – 2024** McGill Engineering Doctoral Awards (MEDA), McGill University

**2021** TISED Doctoral Recruitment Awards (DRA), McGill University

**2019** Outstanding Graduates of Liaoning Province

**2019** Most Influential Graduates, Northeastern University

**2018/2019** Northeastern University 1st Class Academic Scholarship

**2017** National 1st Prize Award, China Undergraduate Mathematical Contest in Modeling

**2016** Northeastern University 2nd Class Academic Scholarship

## OTHER EXPERIENCE

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### **Academic Service**

- **Workshop Organizer:** CVPR 2026 (Video Generative Models: Benchmarks & Evaluation); ICCV 2025 (Memory and Vision); COLM 2025 (AI Agents: Capabilities and Safety).
- **Conference Reviewer:** NeurIPS, ICLR, AISTATS, CVPR, ICCV, COLM, EMNLP, AAAI, IROS, ICRA, ITSC.
- **Journal Reviewer:** IEEE RA-L; Transportation Research Part C (TRC); IEEE T-ITS.